

LMDZ

Dynamics/physics organization,
Grids,
Time stepping,
Dissipation...

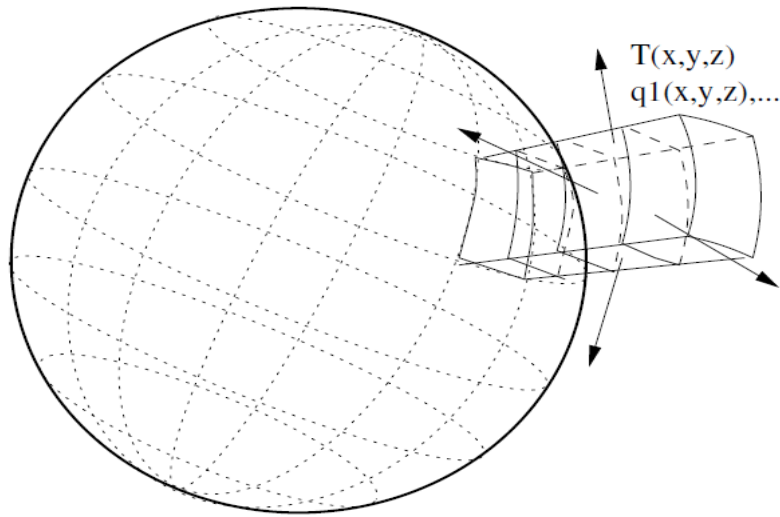
LMDZ courses, January 14, 2026

Overview of course topics

- Grids:
 - Horizontal grids in the physics & dynamics
 - Vertical discretization
- Time marching:
 - Generalities about time marching schemes
 - What is used in LMDZ
 - Longitudinal polar filter
- Lateral diffusion and sponge layer:
 - Energy cascade
 - Illustrative example of diffusion
 - Sponge layer near model top

Grids in LMDZ

Dynamics

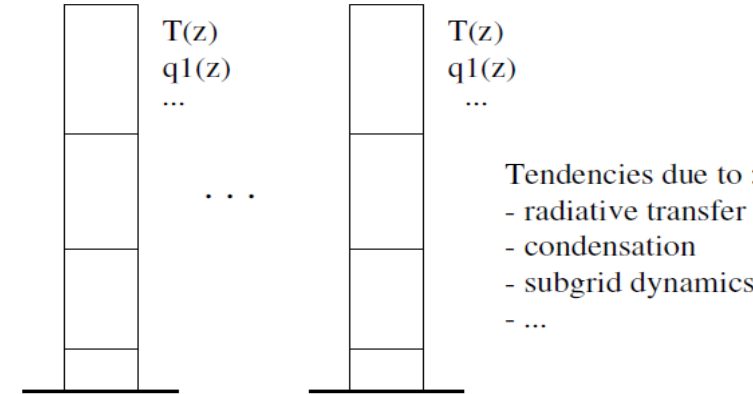


Dynamical tendencies



Physical fields

Physics



Separation between physics and dynamics:

- “**dynamics**”: solving the GFD equations on the sphere; usually with the assumption of a hydrostatic balance and thin layer approximation. Valid for all terrestrial planets.
- “**physics**”: (planet-specific) local processes, local to individual atmospheric columns.

Horizontal grids in LMDZ

Grid dimensions specified when compiling LMDZ:

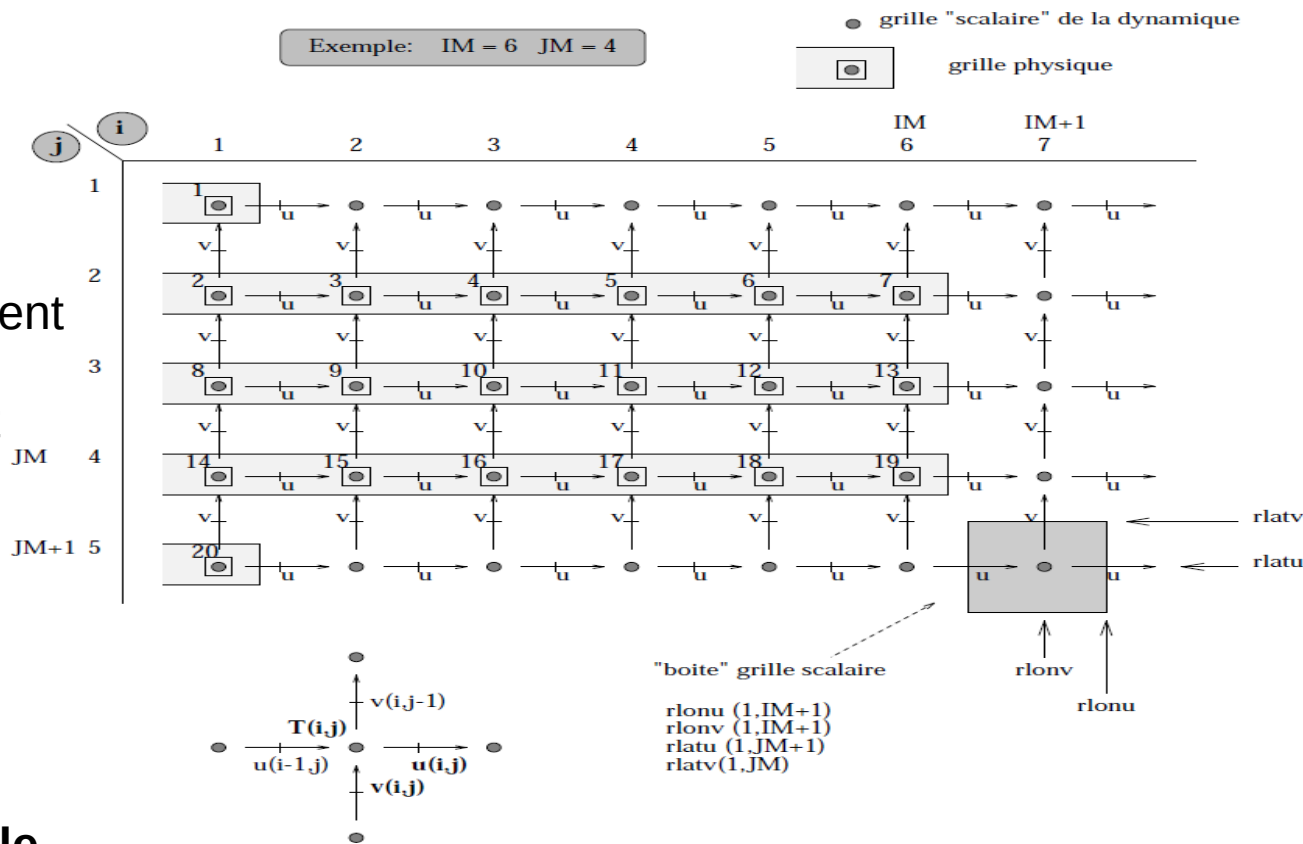
```
makelmdz_fcm -d iimxjjmxllm ...
```

In the dynamics:

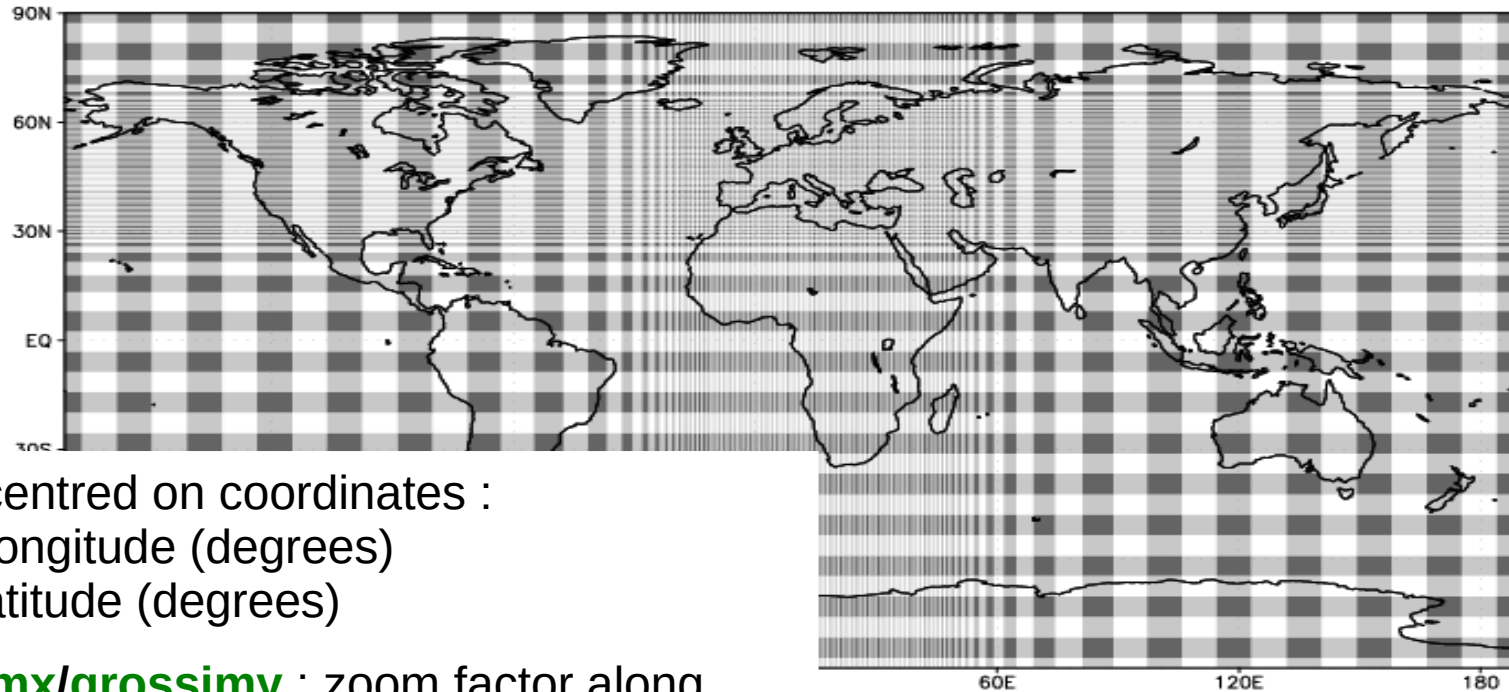
- Staggered grids: **u**, **v** and **scalars** (temperature, tracers) are on different meshes
- Global lonxlat grids with redundant grid points
 - at the poles
 - in longitude

In the physics:

- Collocated variables
- No global lonxlat horizontal grid, columns are labelled **using a single index** (from North Pole to South Pole)



LMDZ, Z for Zoom



Zoom centred on coordinates :

clon : longitude (degrees)

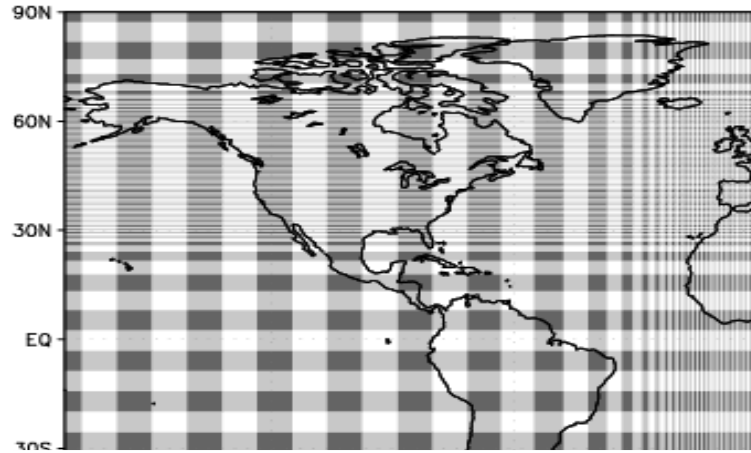
clat : latitude (degrees)

grossimx/grossimy : zoom factor along
x/y directions (i.e. lon/lat)

Computed as the ratio of the smallest mesh (i.e. in the zoom), compared to the mesh size for a global regular grid with the same total number of points.

dzoomx/dzoomy : fraction of the grid containing the zoomed area: $dzoom \times 360^\circ$ by $dzoomy \times 180^\circ$

LMDZ, Z for Zoom



Zoom centred on coordinates :

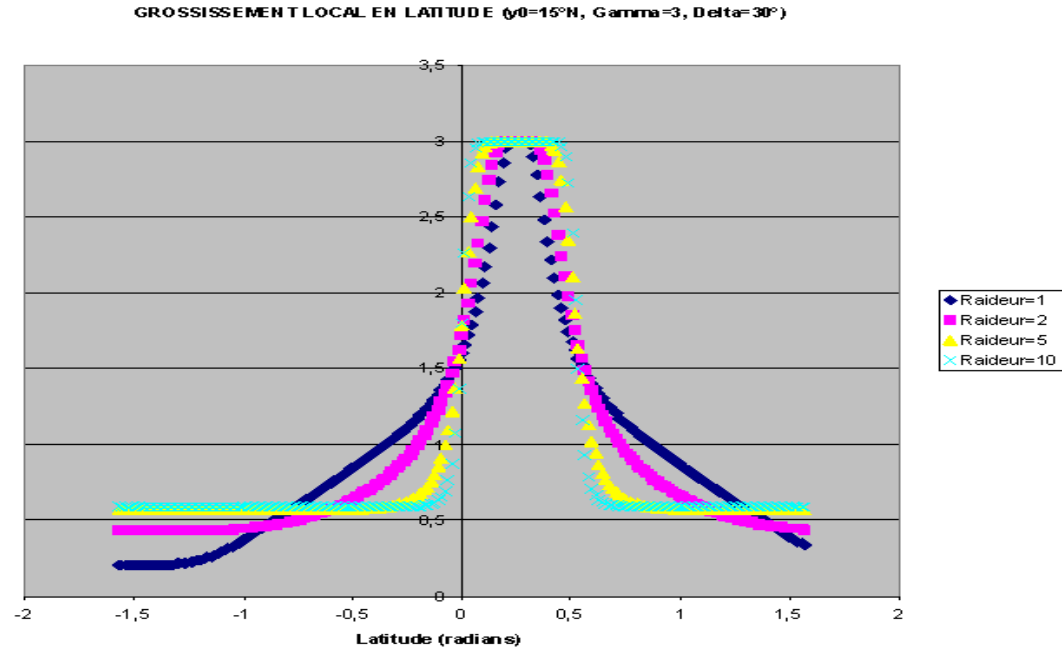
clon : longitude (degrees)

clat : latitude (degrees)

grossimx/grossimy : zoom factor along
x/y directions (i.e. lon/lat)

Computed as the ratio of the smallest mesh (i.e. in the zoom), compared to the mesh size for a global regular grid with the same total number of points.

taux/tauy : steepness of the transition between inner zoom and outer zoom meshes
(typically one tries to avoid sharp transitions; $\tau \sim 3$ is a reasonable value)



Nudging in LMDZ

$$\frac{\partial u}{\partial t} = \frac{\partial u}{\partial t}_{GCM} + \frac{u_{analyse} - u}{\tau}$$
$$\frac{\partial v}{\partial t} = \frac{\partial v}{\partial t}_{GCM} + \frac{v_{analyse} - v}{\tau}$$

Nudging towards
analyses or reanalyses with
chosen time constants

(nudge = “guide”
in French)

Example of nudging parameters:

ok_guide = y

guide_T = n , guide_p = n , guide_q = n

guide_u = y , guide_v = y

tau_min_u = 0.0208333 (days)

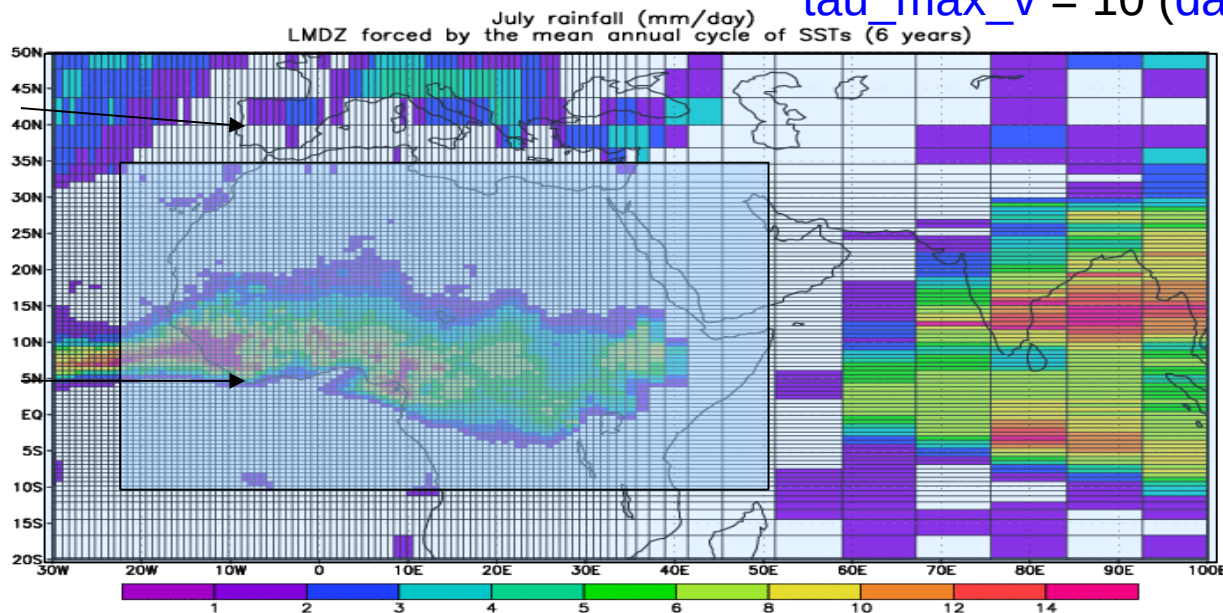
tau_max_u = 10 (days)

tau_min_v = 0.0208333 (days)

tau_max_v = 10 (days)

Strong nudging
($\tau=30\text{min}$)

Weak to
moderate
nudging
($\tau=10\text{ days}$)



Vertical discretization in LMDZ

- Model levels are hybrid **sigma-pressure** levels:

$$P(\text{level}, \text{time}) = \text{ap}(\text{level}) + \text{bp}(\text{level}) \cdot P_s(\text{time})$$

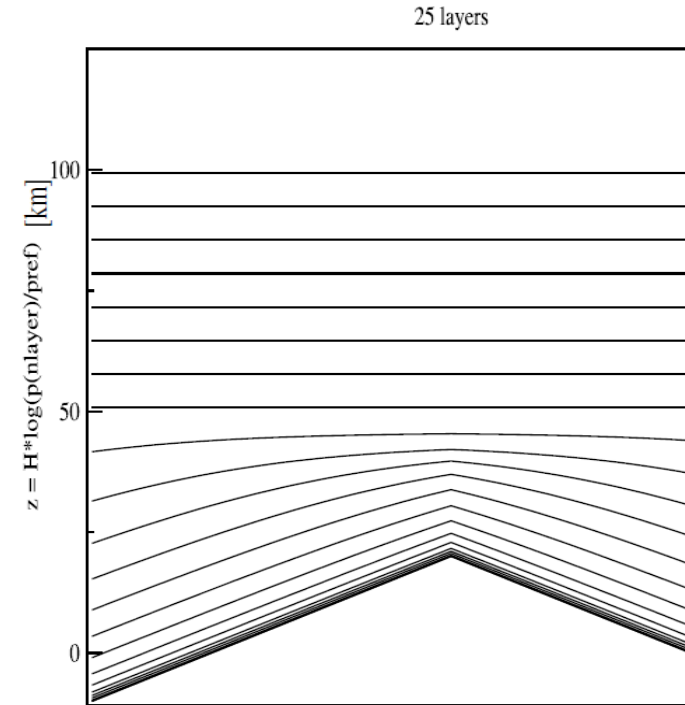
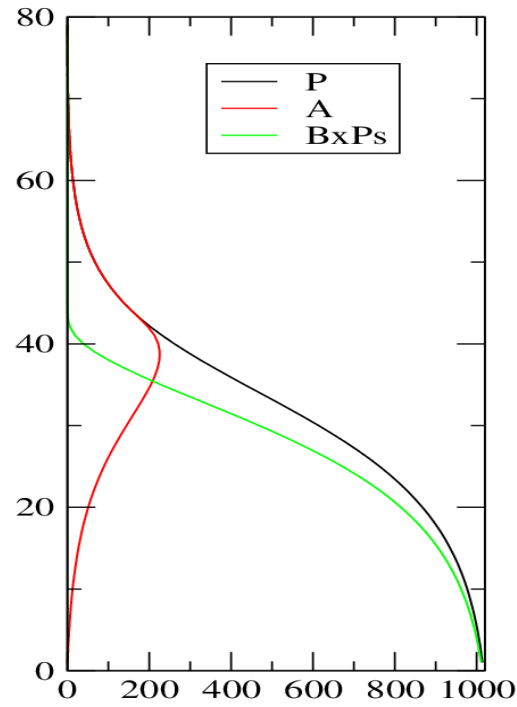
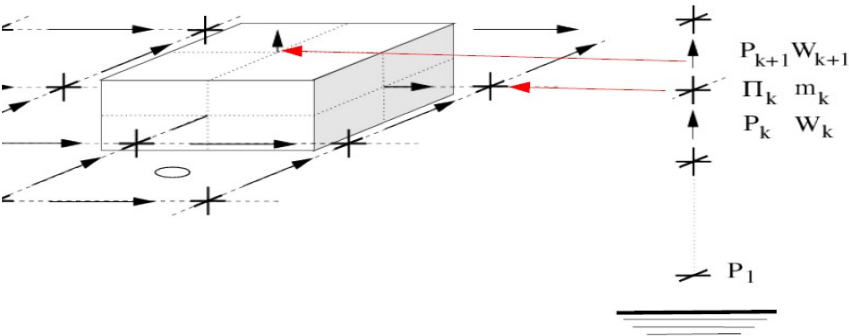
hybrid coordinates $\text{ap}(k)$ and $\text{bp}(k)$ are fixed for a given model run

Surface pressure $P_s(t)$ varies during the run

- Near the surface $\text{ap} \sim 0$

$$\Rightarrow \text{bp}(k) \sim P/P_s$$

- At high altitudes, $\text{bp} \sim 0$



Vertical discretization in LMDZ

- Setting model levels via the def files (also a function of number of vertical levels) :
vert_sampling = strato_custom : customizable (via other parameters in .def file; see next slide) discretization for stratospheric extensions.

Multiple other possibilities from this “default”:

vert_sampling = strato : a default for stratospheric extensions

vert_sampling = sigma : automated generation of purely sigma levels

vert_sampling = param : load values from a “sigma.def” file

vert_sampling = tropo : a default for tropospheric simulations

vert_sampling = read : read ap() and bp() from file “hybrid.txt”

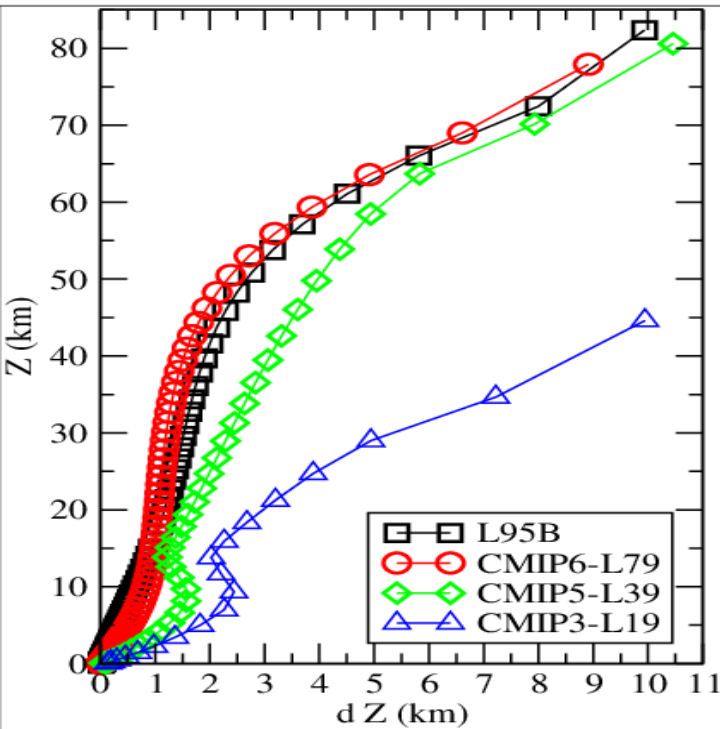
=> Typically you don't need to mess with the vertical discretization,

the default behaviour most likely matches your needs.

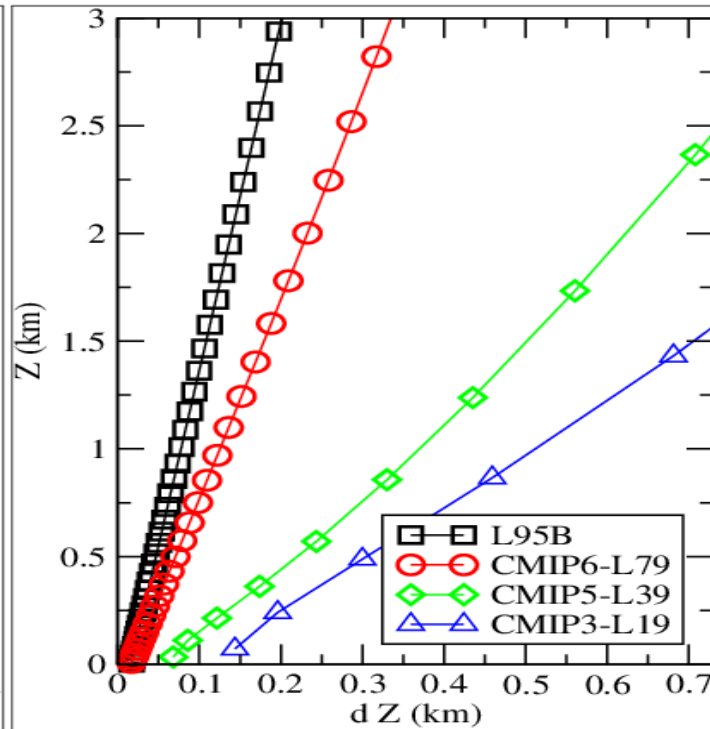
=> Check out routine dyn3d_common/**disvert.F90**

Vertical discretization in LMDZ

Illustration of typical altitudes and layer thickness of L19/L39/L79/L95 grids



Over the whole atmosphere
 $0 < z < \sim 80$ km



Near the surface
 $0 < z < 3$ km

**“Standard” CMIP6
L79 settings
(see DefLists/vert_L79.def)**

`vert_sampling=strato_custom`

`vert_scale=7.`
`vert_dzmin=0.017`
`vert_dzlow=1.`
`vert_z0low=8.7`
`vert_dzmid=2.`
`vert_z0mid=70.`
`vert_h_mid=20.`
`vert_dzhig=11.`
`vert_z0hig=75.`
`vert_h_hig=20.`

Questions ?

Time marching schemes

- **The big picture:** you want to solve

$$\begin{aligned}\frac{df(t)}{dt} &= R(f, t) \\ f(t=0) &= f_0\end{aligned}$$

from a known initial condition at time $t=0$ to time $t=\dots$

- So it is all about using a **time marching** scheme, built on **Taylor expansion** for evaluation of the time derivative, and choosing at which **time level** $t=n.\delta t$ the right hand side term $R[f(t),t]$ is to be evaluated :

$$f(t_0 + \delta t) = f(t_0) + \frac{\delta t}{1!} f'(t_0) + \frac{(\delta t)^2}{2!} f''(t_0) + \dots$$

Time marching schemes

- **Explicit Euler** scheme (1st order in time):

$$\frac{df(t)}{dt} \simeq \frac{f_{n+1} - f_n}{\delta t}$$
$$R(f, t) \simeq R(f(t_n), t_n)$$

- **Implicit Euler** scheme (1st order in time):

$$\frac{df(t)}{dt} \simeq \frac{f_{n+1} - f_n}{\delta t}$$
$$R(f, t) \simeq R(f(t_{n+1}), t_{n+1})$$

- **Crank-Nicholson** scheme (2nd order in time):

$$\frac{df(t)}{dt} \simeq \frac{f_{n+1} - f_n}{\delta t}$$
$$R(f, t) \simeq \frac{R(f(t_{n+1}), t_{n+1}) + R(f(t_n), t_n)}{2}$$

Time marching schemes

- **Matsuno** scheme: a predictor-corrector (Euler explicit-Euler Implicit) scheme (1st order):

$$\begin{aligned}\frac{df(t)}{dt} &\simeq \frac{f_{n+1} - f_n}{\delta t} \\ f^p(t_{n+1}) &= f(t_n) + \delta t \cdot R(f(t_n), t_n) \\ R(f, t) &\simeq R(f^p(t_{n+1}), t_{n+1})\end{aligned}$$

- **Leapfrog** scheme: use encompassing time steps to evaluate the derivative (2nd order):

$$\begin{aligned}\frac{df(t)}{dt} &\simeq \frac{f_{n+1} - f_{n-1}}{2\delta t} \\ R(f, t) &\simeq R(f(t_n), t_n)\end{aligned}$$

Time marching schemes

- Illustrative example, on a decay equation (known solution!)

$$\frac{dq(t)}{dt} = -\frac{1}{\tau}q(t) \longrightarrow q(t) = q_0 e^{-\frac{t}{\tau}}$$

- Building Euler explicit (E) & implicit (I) schemes:

$$\begin{aligned}\frac{dq(t)}{dt} &= -\frac{1}{\tau}q(t) \\ \Rightarrow \frac{q^{n+1} - q^n}{\delta t} &\simeq -\frac{1}{\tau}q^n \quad (\text{E.E.}) \\ \Leftrightarrow q^{n+1} - q^n &= -\frac{\delta t}{\tau}q^n \\ \Leftrightarrow q^{n+1} &= \left[1 - \frac{\delta t}{\tau}\right] q^n\end{aligned}$$

$$\begin{aligned}\frac{dq(t)}{dt} &= -\frac{1}{\tau}q(t) \\ \Rightarrow \frac{q^{n+1} - q^n}{\delta t} &\simeq -\frac{1}{\tau}q^{n+1} \quad (\text{E.I.}) \\ \Leftrightarrow q^{n+1} - q^n &= -\frac{\delta t}{\tau}q^{n+1} \\ \Leftrightarrow \frac{\tau + \delta t}{\tau}q^{n+1} &= q^n \\ \Leftrightarrow q^{n+1} &= \frac{1}{1 + \frac{\delta t}{\tau}}q^n\end{aligned}$$

Time marching schemes

- Illustrative example, on a decay equation

$$\frac{dq(t)}{dt} = -\frac{1}{\tau}q(t) \longrightarrow q(t) = q_0 e^{-\frac{t}{\tau}}$$

- Resulting integration schemes:

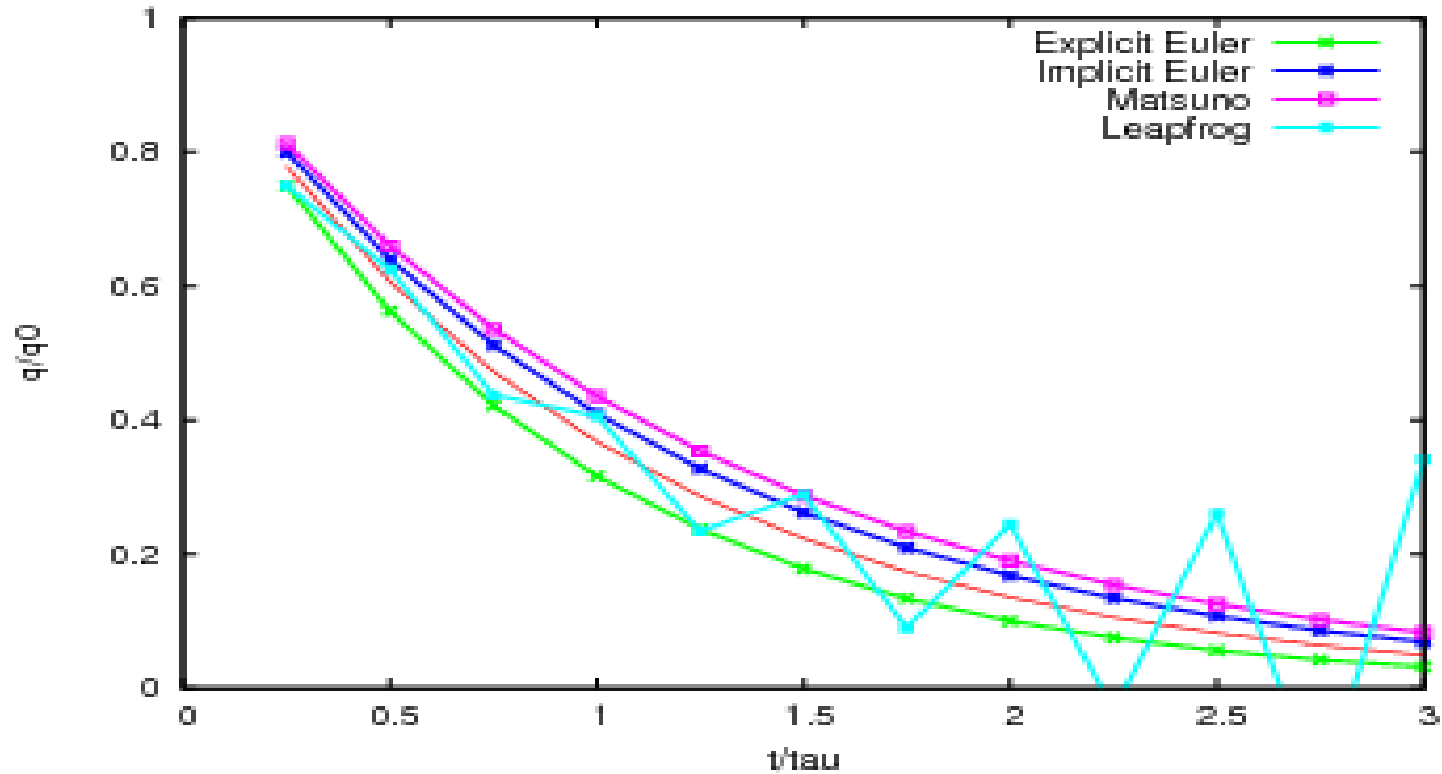
$$\text{EE : } q^{n+1} = \left[1 - \frac{\delta t}{\tau} \right] q^n$$

$$\text{EI : } q^{n+1} = \left[\frac{1}{1 + \delta t/\tau} \right] q^n$$

$$\text{CN : } q^{n+1} = \left[\frac{1 - \delta t/(2\tau)}{1 + \delta t/(2\tau)} \right] q^n$$

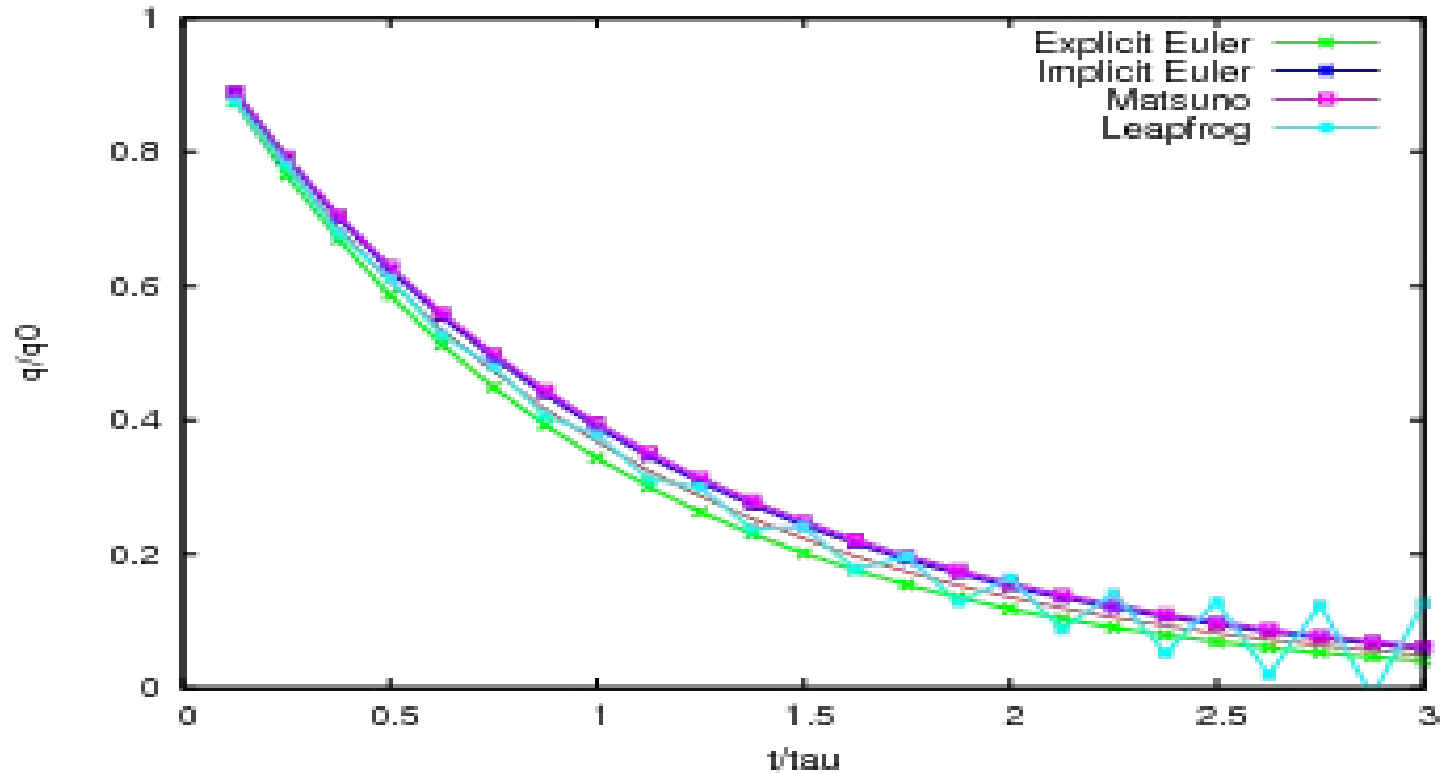
- Stability requirement (CFL) for EE : $\delta t/\tau < 2$

Time marching schemes



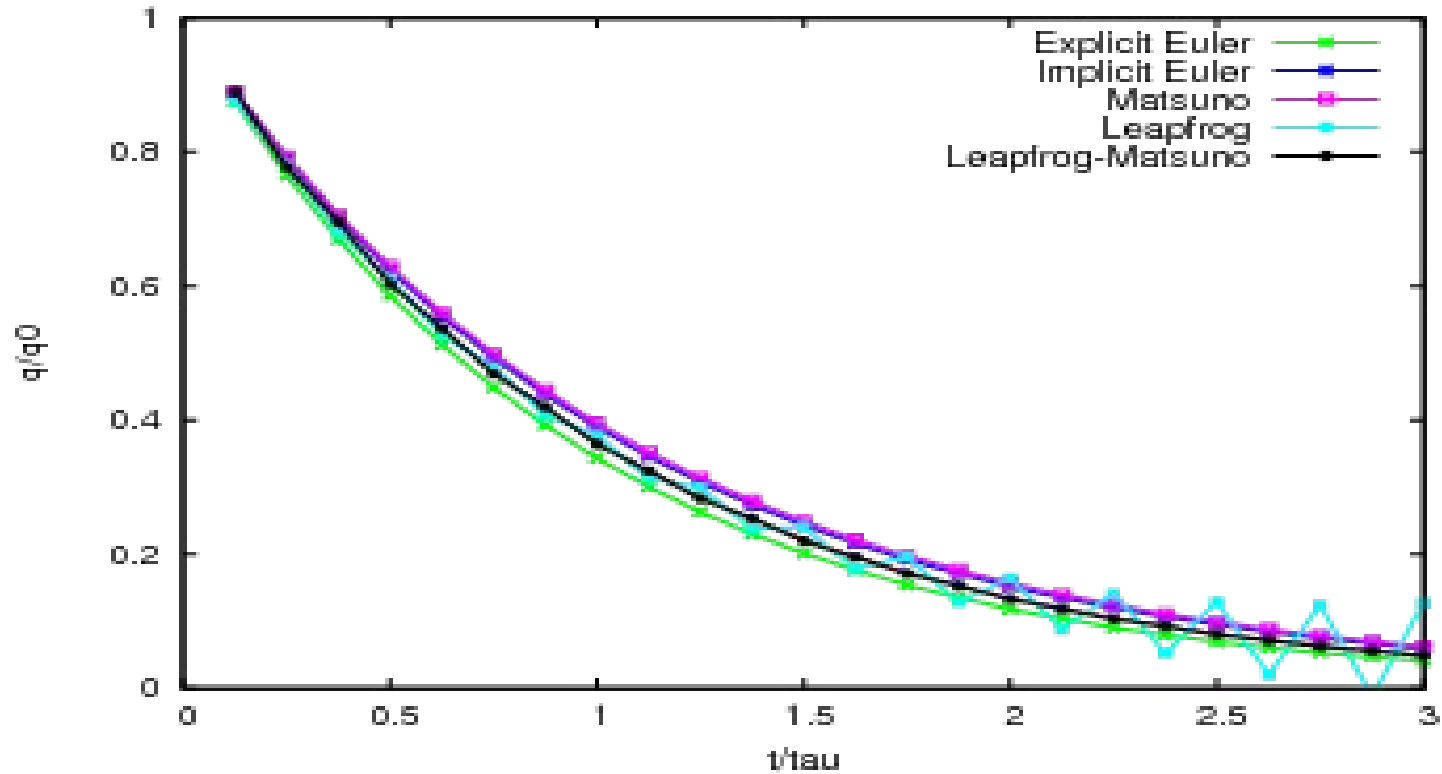
- 4 integration steps per unit of t/τ

Time marching schemes



- 8 integration steps per unit of t/τ

Time marching schemes



- 8 integration steps per unit of t/τ

Time marching in LMDZ

Time splitting between physics/dynamics/dissipation:

$$\frac{\partial \psi}{\partial t} = Dyn(\psi) + Phy(\psi) + Dissip(\psi)$$

- **Dynamics** : Leapfrog-Matsuno scheme

Using **day_step** dynamical steps per day

Leapfrog steps with a Matsuno step every **iperiod** step

- **Physics** : Explicit Euler

Every **iphysiq** dynamical steps (multiple of iperiod)

- **Dissipation**: Explicit Euler

Every **dissip_period** dynamical steps (multiple of iperiod)

Side note about explicit or implicit time marching schemes

Even when solving linear spatio-temporal boundary-value problems, e.g.:

$$\frac{dA}{dt} = \kappa \frac{\partial^2 A}{\partial x^2}$$

The **explicit Euler** approach leads to a straightforward expression for grid point values (but with stability constraints) :

$$\frac{A_i^{k+1} - A_i^k}{\delta t} = \frac{\kappa}{h^2} [A_{i-1}^k - 2A_i^k + A_{i+1}^k]$$

Whereas the **implicit Euler** approach leads to a (tridiagonal) system of equations to solve:

$$\frac{A_i^{k+1} - A_i^k}{\delta t} = \frac{\kappa}{h^2} [A_{i-1}^{k+1} - 2A_i^{k+1} + A_{i+1}^{k+1}]$$

=> **requires more computations**, but may be necessary if time-stepping constraints require using large time steps.

Side note about tridiagonal system solving

When needing to solve a tridiagonal system of the form:

$T.x=y$, T tridiagonal matrix, x & y vectors

Rather than invert T (costly!) to generate T^{-1} (dense matrix) and then compute $x=T^{-1}.y$ (matrix-vector product)

Use the LU decomposition (Gaussian elimination) of T to split the problem into two very simple sub-problems:

- 1) $L.U=T$, L and U are bidiagonal (lower/upper) matrices
- 2) Solve $L.z=y$ for vector z (forward substitution step)
- 3) Solve $U.x=z$ for vector x (backward substitution step)

Side note about incorporating boundary conditions (BC)

$$\frac{\partial f(x, t)}{\partial t} = R(f, x, t) \text{ with BC: } f(x_B, t) = B(x_B, t)$$

- In practice one needs to **treat specifically** the spatial boundary conditions, which could be either imposed on the value (Dirichlet) or its derivative (Neumann) or a mix of the two (Robin) or ...
- The choice of using an implicit or explicit representation also impacts the incorporation of the boundary conditions (along spatial directions)

$$\text{Explicit (B}_n \text{ known)} \Rightarrow \frac{f_{n+1} - f_n}{\delta t} \simeq R_n \text{ with BC: B}_n$$

$$\text{Implicit (B}_{n+1} \text{ unknown)} \Rightarrow \frac{f_{n+1} - f_n}{\delta t} \simeq R_{n+1} \text{ with BC: B}_{n+1}$$

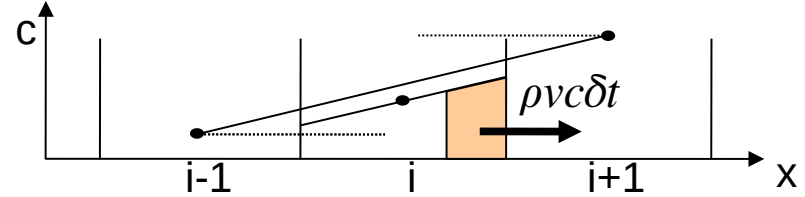
Tracer advection in LMDZ

Use of the [Van Leer I scheme](#) (1977), a second order finite volume scheme with slope limiters (e.g. MUSCL, MINMOD) (Hourdin et Armengaud, 1999).

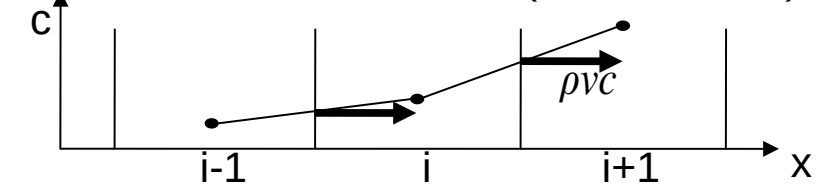
Guaranties of fundamental physical properties of transport :
conservation of the total quantity,
positivity, monotony, non amplification
of extrema, weak numerical diffusion

- **CFL requirement**, for an advection velocity U_{\max} :
 $U_{\max} \cdot (dt/dx) = cte$, with $cte \sim 0(1)$

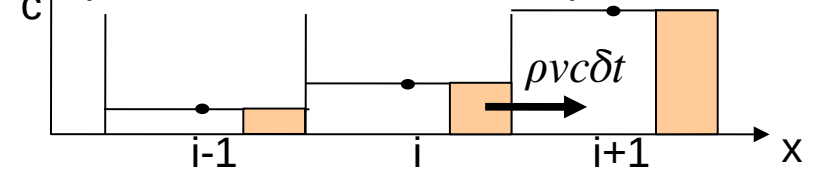
Scheme I by Van Leer (1977)



Centered finite differences (second order)



Upwind first order scheme (Godunov, 1952)



Tracer advection in LMDZ

- In practice: Tracer names and various properties are set in the `tracer.def` file. e.g.:

`&version=1.0`

`&lmdz`

`default type=tracer phases=g hadv=10 vadv=10 parent=air`

`H2O phases=g hadv=14 vadv=14`

`H2O phases=l hadv=10 vadv=10`

`H2O phases=s hadv=10 vadv=10`

`Rn`

`Pb`

- Scheme “10” : Van Leer scheme
- Scheme “14” : Dedicated modified scheme for water vapor
- Other (experimental) schemes are coded; see [dyn3d/advtrac.F90](#)

Tracer advection in LMDZ

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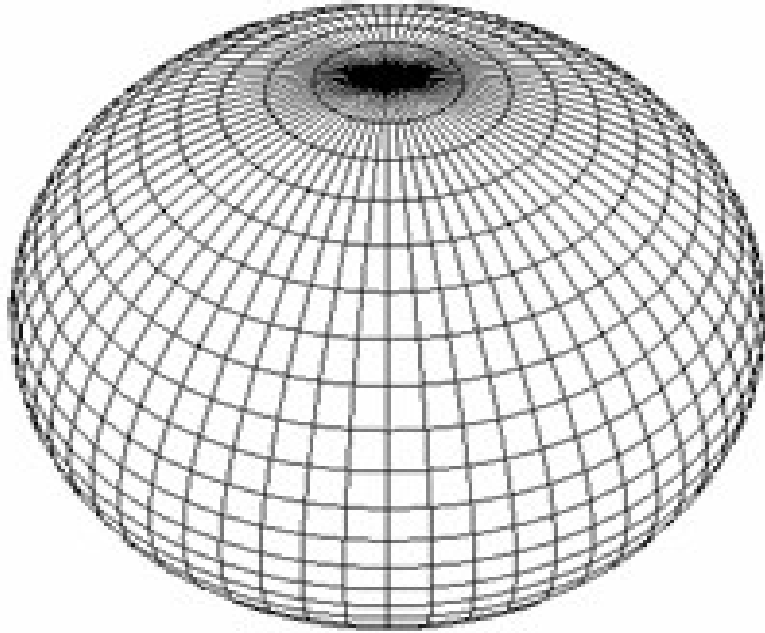
`Rn`

`Pb`

- `phases`: gas/liquid/solid for a given tracer
- `parent`: air or another tracer (for isotopes)+ possibility of “tagging”
see <https://lmdz-forge.lmd.jussieu.fr/mediawiki/LMDZPedia>

Questions ?

The longitudinal polar filter



- A lon-lat grid implies that the **meshes tighten dramatically** as the pole is approached.
- **CFL conditions** there would dictate using an extremely small time step for the time marching scheme.
- **Longitudinal** (Fourier) **filtering**, removing high spatial frequencies, is used to enforce that resolved features are at the level of those at $\sim 60^\circ$ (where longitudinal resolution is half of that at the equator).
- In addition near the poles there is some longitudinal grouping of meshes (applied to the divergence of air transport) by bunches of 2^{ngroup} (typically $\text{ngroup}=3$) which implies that the number of points along longitudes of the GCM must be a multiple of 2^{ngroup} !

Energy spectra and lateral dissipation

- Observations (Nastrom & Gage 1985, Lindborg 1999) collected over length scales from a few to thousands of km display a **characteristic energy cascade** (from Skamarock, 2004).

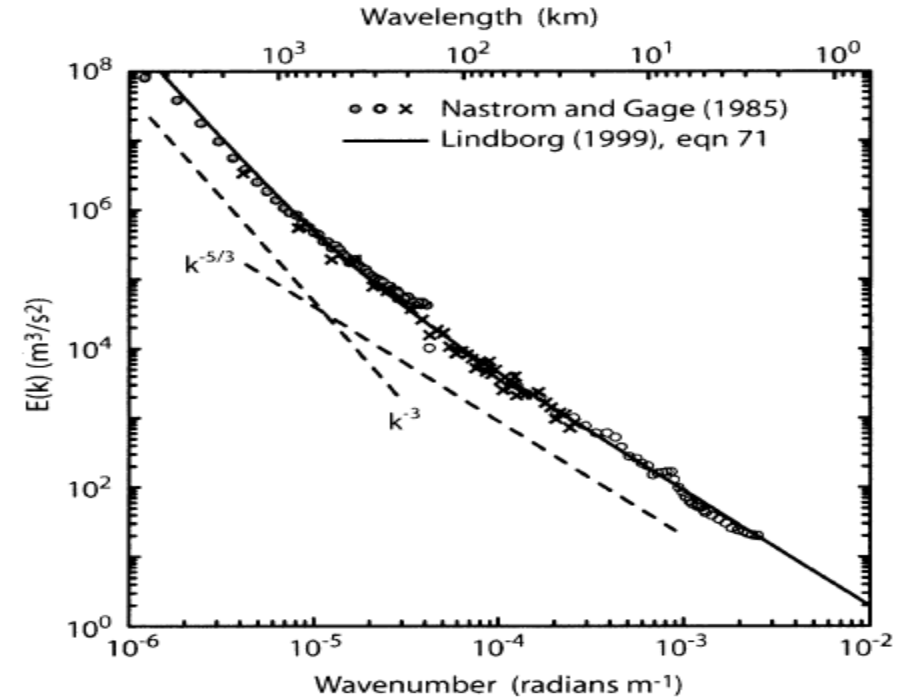


FIG. 1. Nastrom and Gage (1985) spectrum derived from the GASP aircraft observations (symbols) and the Lindborg (1999) functional fit to the MOZAIC aircraft observations.

- In order to fulfil the observed energy cascade from resolved scales to unresolved scales in GCMs, a **dissipation term** is added:

$$Dissip(\psi) = \frac{(-1)^{q+1}}{\tau} \nabla^{2q} \psi$$

Lateral dissipation in GCMs as a tool to pin the energy cascade

Figures from *Numerical Techniques for Global Atmospheric Models*, Lauritzen et al. (eds), 2010

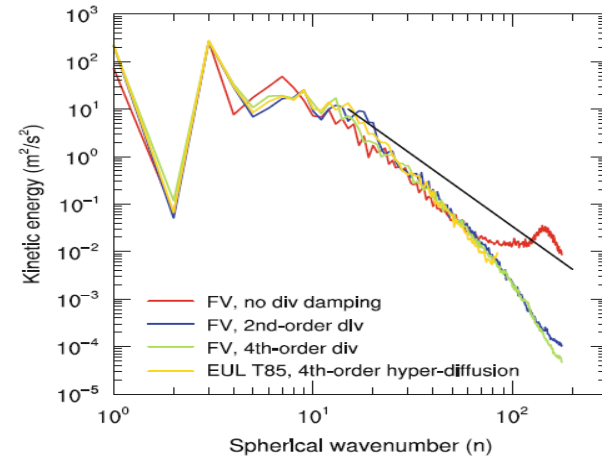
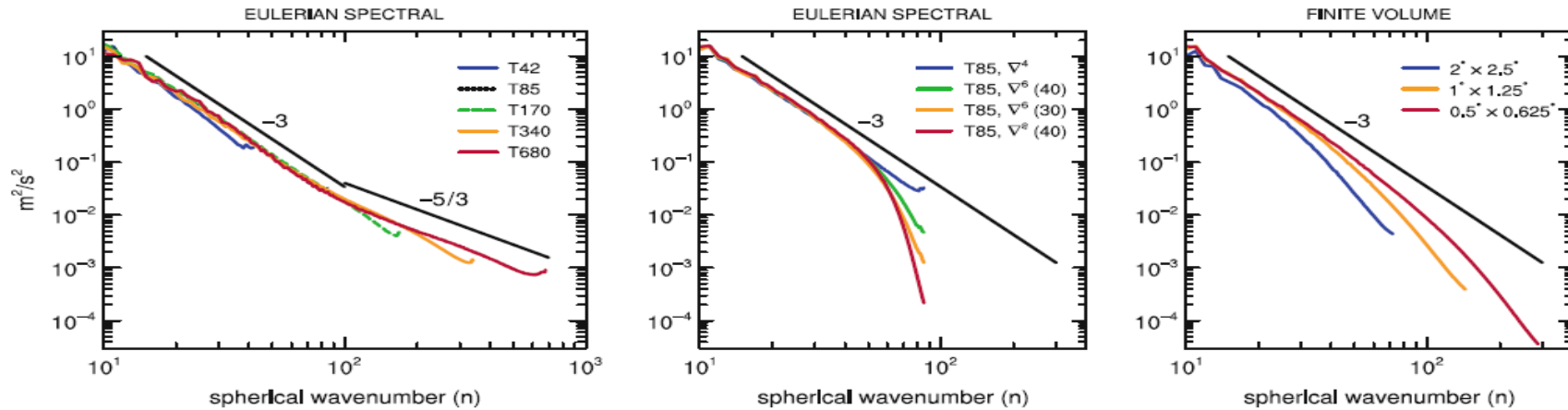


Fig. 13.4 250 hPa kinetic energy spectra as a function of the spherical wavenumber (n) in aquaplanet simulations from (left) CAM Eulerian spectral dynamical core with ∇^4 diffusion for different resolutions, (center) T85L26 Eulerian spectral dynamical with ∇^4 , ∇^6 and ∇^8 diffusion, and (right) CAM Finite Volume (FV) dynamical core for different $lat \times lon$ resolutions in degrees and 26 levels

Illustrative example of dissipation

- Simple 1D diffusion equation toy model:

$$\frac{dA}{dt} = \nu \frac{\partial^2 A}{\partial x^2}$$

- Von Neumann (Fourier mode) analysis

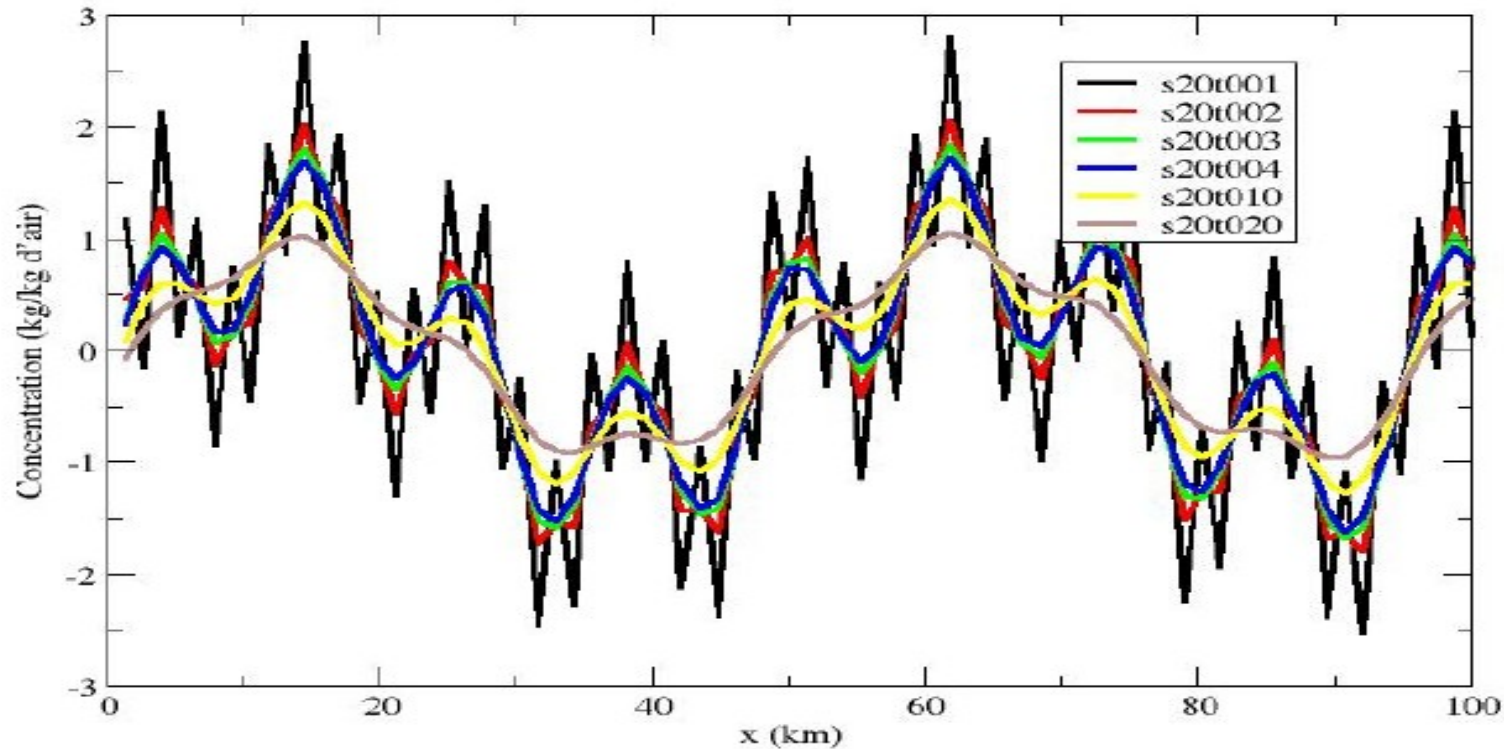
$$A_k(t) = a_k(t) \cdot \sin(kx)$$

- **Explicit Euler** time marching (with stability condition!):

$$a_k^{n+1} = (1 - \nu k^2 \Delta t) a_k^n$$

Note that mode damping is stronger for large k

Illustrative example of dissipation



Temporal evolution, from an initial condition consisting of 2 sine modes and an extreme (2 grid points wavelength) “numerical mode”

Controlling dissipation in LMDZ

- Parameters in file gcm.def:

dissip_period: Apply dissipation every dissip_period dynamical steps (or specify 0 to let model pick an appropriate value)

nitergdiv: number of iterations on velocity dissipation operator grad.div

nitergrot: number of iterations on velocity dissipation operator grad.rot

niterh: number of iterations on temperature dissipation operator div.grad

Usual values: nitergdiv=1, nitergrot=2, niterh=2

tetagdiv: dissipation time scale (s) for smallest wavelength for u,v (grad.div component)

tetagrot: dissipation time scale (s) for smallest wavelength for u,v (grad.rot component)

tetatemp: dissipation time scale (s) for smallest wavelength for potential temperature (div.grad)

values depend on horizontal resolution

Controlling dissipation in LMDZ

- Parameters in file gcm.def:

tetagdiv: dissipation time scale (s) for smallest wavelength for u,v (grad.div component)

tetagrot: dissipation time scale (s) for smallest wavelength for u,v (grad.rot component)

tetatemp: dissipation time scale (s) for smallest wavelength for potential temperature (div.grad)

optimal tetat values depend on horizontal resolution

- Moreover there is a multiplicative factor for the dissipation coefficient, which increases with model levels (see dyn3d_common/**inidissip.F90**), which can be controlled by flag “vert_prof_dissip”

The sponge layer

- In addition to lateral dissipation, it is necessary to damp vertically propagating waves (non-physically reflected downward from model top).
- The **sponge layer is limited to topmost layers** (usually 4) and added during the dissipation step.
- Sponge modes and parameters (gcm.def):

iflag_top_bound: 0 for no sponge, 1 for sponge over 4 topmost layers, 2 for sponge from top to 100 times topmost layer pressure

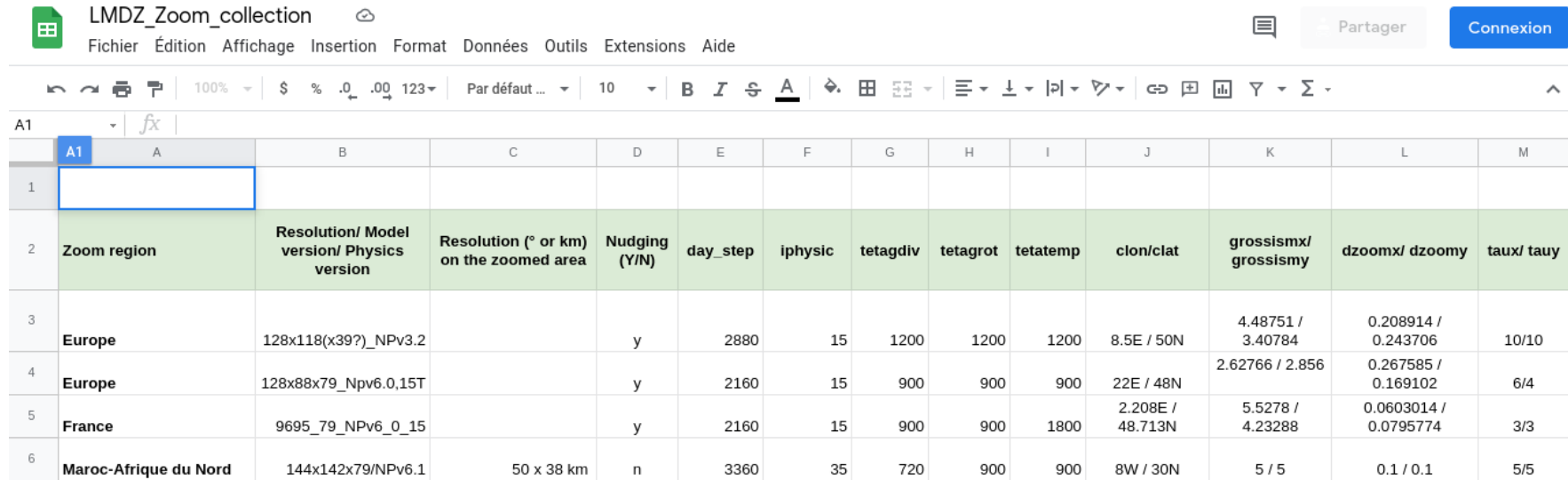
mode_top_bound: 0 for no relaxation, 1 to relax u,v to zero, 2 to relax u,v to their zonal mean, 3 to relax u,v and potential temperature to their zonal mean.

tau_top_bound: inverse of characteristic time scale at the topmost layer (halved at each successive descending layer)

Where to get typical values of the run.def/gcm.def parameters

- Check out the various examples of `gcm.def_*` files located in the **LMDZ/DefLists** subdirectory
- Some examples of specific cases of Zoomed simulation setups are detailed in a collaborative document; get the link by searching “Zoom collection” on LMDZPedia :

<https://lmdz-forge.lmd.jussieu.fr/mediawiki/LMDZPedia>



The screenshot shows a Google Sheet titled "LMDZ_Zoom_collection". The table contains the following data:

	A	B	C	D	E	F	G	H	I	J	K	L	M
1													
2	Zoom region	Resolution/ Model version/ Physics version	Resolution (° or km) on the zoomed area	Nudging (Y/N)	day_step	iphysic	tetagdiv	tetagrot	tetatemp	clon/clat	grossismx/ grossismy	dzoomx/ dzoomy	taux/ tauy
3	Europe	128x118(x39?)_NPv3.2		y	2880	15	1200	1200	1200	8.5E / 50N	4.48751 / 3.40784	0.208914 / 0.243706	10/10
4	Europe	128x88x79_Npv6.0,15T		y	2160	15	900	900	900	22E / 48N	2.62766 / 2.856	0.267585 / 0.169102	6/4
5	France	9695_79_NPv6_0_15		y	2160	15	900	900	1800	2.208E / 48.713N	5.5278 / 4.23288	0.0603014 / 0.0795774	3/3
6	Maroc-Afrique du Nord	144x142x79/NPv6.1	50 x 38 km	n	3360	35	720	900	900	8W / 30N	5 / 5	0.1 / 0.1	5/5

Some rules of thumb for run.def parameters

- Time steps in LMDZ:

dynamical time steps: $\text{dtvr} = \text{daysec} / \text{day_step}$

physics time step: $\text{dtphys} = \text{iphysiq} * \text{dtvr}$

dissipation time step: $\text{dtdiss} = \text{dissip_period} * \text{dtvr}$

tracer advection time step: $\text{dtvrtrac} = \text{iapp_trac} * \text{dtvr}$

- Constraints to be aware of:

dtvr limited by CFL for waves: $C_{\text{max}}.dt < \min(dx, dy)$

dtrtrac limited by advection CFL: $U_{\text{max}}.dt < \min(dx, dy)$

iphysiq , dtvrtrac , dissip_period should be multiples of iperiod

Some rules of thumb for run.def parameters

- Constraints to be aware of (continued):
dissipation time step should be much smaller than dissipation timescales:
 $\text{dtdiss} \ll \text{tetatgdiv}, \text{tetagrot}, \text{tetatemp}$
- Changing time step with resolution on a regular grid:
 $\text{day_step}(\max(\text{iim}, \text{jjm})=N) \sim \text{day_step}(\max(\text{iim}, \text{jjm})=M) * M/N$
- Time step for a zoomed simulation, compared to regular grid:
 $\text{day_step}(\text{zoom}) \sim \text{day_step}(\text{regular}) * \max(\text{grossismx}, \text{grossismy})$

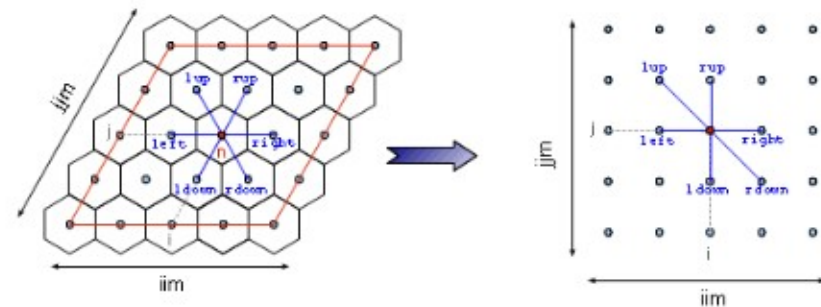
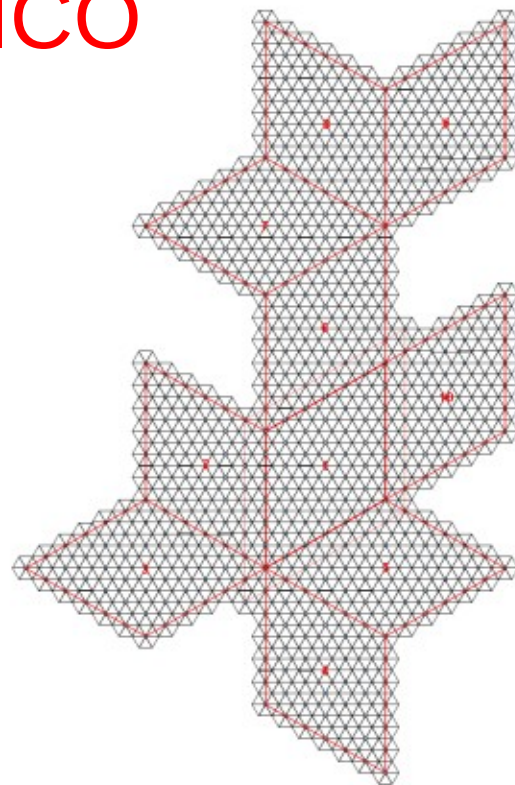
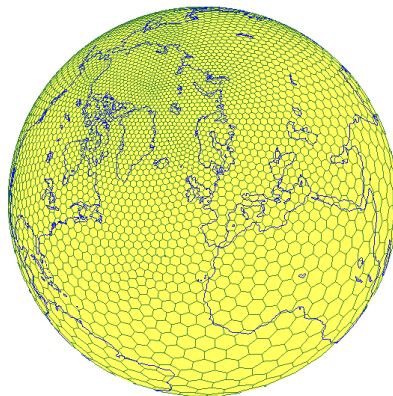
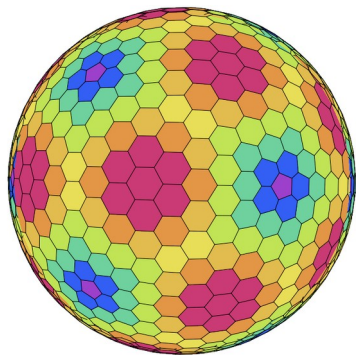
LMDZ + DYNAMICO

An icosahedral grid...

- Cells are mostly (irregular) hexagons, some pentagons
- No zonal filters => more parallelism
- Makes other things trickier !

.. but a similar “user experience”.

*Especially, files are read/written by XIOS which can interpolate between DYNAMICO and lon-lat mesh. Except for a good reason, **input and output fields are longitude-latitude***



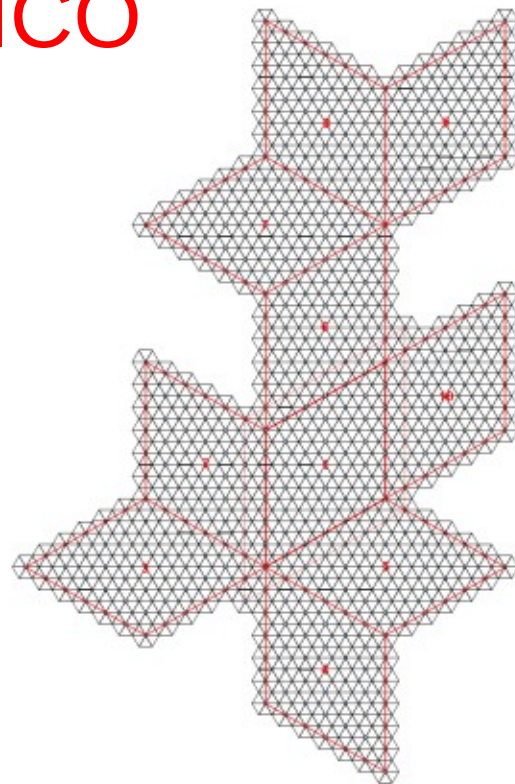
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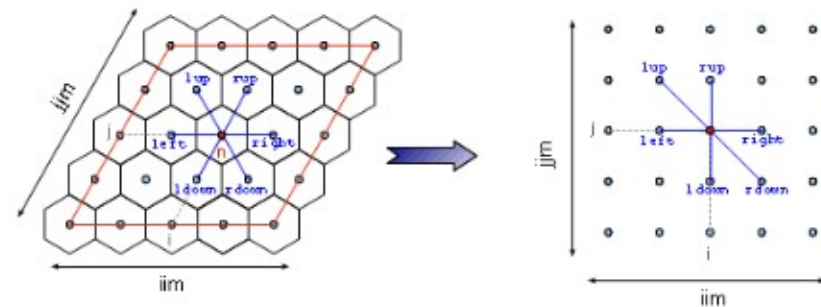
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Horizontal resolution

- Controlled by a single parameter “nbp”
- 10 x nbp x nbp grid points (atmospheric columns)
- nbp=40 => about 2 degree resolution (dx ~ 220km)
- dx is divided by 2 when nbp doubles
- maximum dynamics time step: $dt \sim dx/c$, $c \sim 400$ m/s



LMDZ + DYNAMICO

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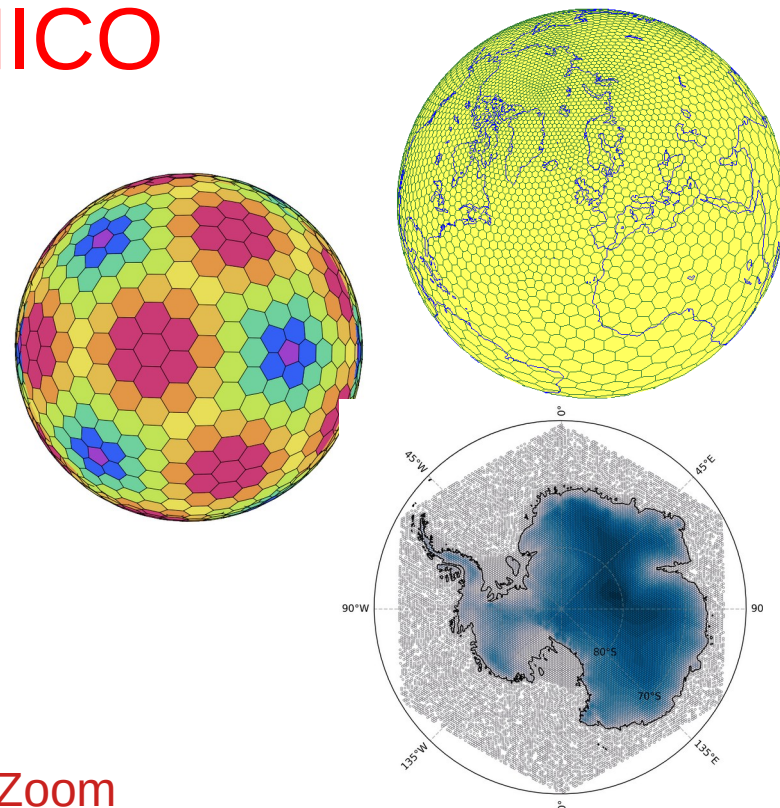
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Zoom

- “polar” zoom via Schmidt transform
- soon (?) via variable-resolution meshing

Limited Area-Model

- metric_type = icoso_area
- set center (lon, lat) and radius
- dx = radius/nbp
- Needs other parameters, and **input files**

LMDZ + DYNAMICO

Transport schemes

- Scheme similar to lon-lat Van Leer
- Transport time step can be a small multiple of dynamics time step ([itau_adv](#))

Horizontal dissipation

- (bi-)laplacian, exactly as lon-lat LMDZ
- Coefficients tuned for a certain resolution

Sponge layer

- Relaxation to zero: simple but breaks total angular momentum conservation
- Relaxation to zonal mean: implemented (via [XIOS](#)) by expensive...
- Relaxation to temporal mean: implemented (via [XIOS](#)), local, so less expensive

Nudging

- implemented

(incomplete) doc of DYNAMICO parameters/flags:

https://gitlab.in2p3.fr/ipsl/projets/dynamico/dynamico/-/blob/master/PARAMETERS.md?ref_type=heads

Search for DYNAMICO on [LMDZPedia](#)!:

<https://lmdz-forge.lmd.jussieu.fr/mediawiki/LMDZPedia/index.php/Sp%C3%A9cial:Recherche?search=dynamico&fulltext=Recherche+en+texte+int%C3%A9gral&fulltext=Search>